

# Smallest Equilibrium Implementation in Binary-Action Supermodular Games

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# Paper

- ▶ Morris, S., D. Oyama, and S. Takahashi (2020).  
“Implementation via Information Design in Binary-Action Supermodular Games.”

## Base Game

We fix the base game:

- ▶  $I = \{1, \dots, |I|\}$ : Set of players
- ▶  $A_i = \{0, 1\}$ : Binary action set for  $i$       ( $A = A_1 \times \dots \times A_{|I|}$ )
- ▶  $\Theta$ : Finite set of states
- ▶  $\mu \in \Delta(\Theta)$ : Probability distribution over  $\Theta$   
Assume full support:  $\mu(\theta) > 0$  for all  $\theta \in \Theta$
- ▶  $u_i: A \times \Theta \rightarrow \mathbb{R}$ :  $i$ 's payoff function, supermodular:

$$d_i(a_{-i}, \theta) = u_i(1, a_{-i}, \theta) - u_i(0, a_{-i}, \theta)$$

increasing in  $a_{-i}$

- ▶ Dominance state:

There exists  $\bar{\theta} \in \Theta$  such that  $d_i(\mathbf{0}_{-i}, \bar{\theta}) > 0$  for all  $i \in I$ .

# Information Structures

- ▶  $T_i$ : Set of types of player  $i$  (finite or countably infinite)  
( $T = T_1 \times \cdots \times T_{|I|}$ )

- ▶  $\pi \in \Delta(T \times \Theta)$ : Common prior, consistent with  $\mu$ :

$$\sum_t \pi(t, \theta) = \mu(\theta)$$

for all  $\theta \in \Theta$ .

- ▶ Together with the base game, an information structure  $\mathcal{T} = ((T_i)_{i \in I}, \pi)$  defines an incomplete information game:
  - ▶  $\sigma_i: T_i \rightarrow \Delta(A_i)$ : Strategy of player  $i$
  - ▶ Bayes Nash equilibrium (BNE) is defined as usual.
  - ▶  $E(\mathcal{T})$ : Set of BNEs.
  - ▶  $\underline{\sigma} = (\underline{\sigma}_i)_{i \in I}$ : Smallest (pure-strategy) BNE
- ▶ The *outcome*  $\nu \in \Delta(A \times \Theta)$  induced by information structure  $\mathcal{T}$  and strategy profile  $\sigma$ :

$$\nu(a, \theta) = \sum_t \pi(t, \theta) \prod_{i \in I} \sigma_i(t_i)(a_i).$$

- ▶ Outcome  $\nu$  satisfies *consistency* if  $\sum_{a \in A} \nu(a, \theta) = \mu(\theta)$  for all  $\theta \in \Theta$ .

# Partial Implementation

## Definition 1

Outcome  $\nu$  is *partially implementable* if there exist an information structure  $\mathcal{T}$  and an equilibrium  $\sigma \in E(\mathcal{T})$  that induce  $\nu$ .

## Proposition 1

*Outcome  $\nu$  is partially implementable if and only if it is a Bayes correlated equilibrium.*

- ▶ *BCE*: Set of partially implementable outcomes, or equivalently Bayes correlated equilibria

# Smallest Equilibrium Implementation (S-Implementation)

## Definition 2

Outcome  $\nu$  is **S-implementable** if there exists an information structure  $\mathcal{T}$  such that  $(\mathcal{T}, \underline{\sigma})$  induces  $\nu$ .

## Definition 3

Outcome  $\nu$  is **fully implementable** if there exists an information structure  $\mathcal{T}$  such that  $(\mathcal{T}, \sigma)$  induces  $\nu$  for all  $\sigma \in E(\mathcal{T})$ .

- ▶  $SI$ : Set of S-implementable outcomes
- ▶  $FI$ : Set of fully implementable outcomes
- ▶  $FI \subset SI \subset BCE$

## Two-Player Two-State Example (Symmetric Payoffs)

- ▶  $I = \{1, 2\}$
- ▶  $A_1 = A_2 = \{NI, I\}$
- ▶  $\Theta = \{B, G\}$ ,  $\mu(B) = \mu(G) = \frac{1}{2}$
- ▶ Payoffs:

	<i>B</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		-1	$-1 + \varepsilon$

	<i>G</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		$x$	$x + \varepsilon$

- ▶  $\varepsilon > 0$  (supermodularity)
- ▶  $0 < x < 1$ ,  $\varepsilon < \frac{1}{2}(1 - x)$
- ▶ Designer's objective: maximize the number of players who invest.



## Optimal BCE

<i>B</i>	<i>NI</i>	<i>I</i>
<i>NI</i>	$\frac{1-x-2\varepsilon}{2(1-\varepsilon)}$	0
<i>I</i>	0	$\frac{x+\varepsilon}{2(1-\varepsilon)}$

<i>G</i>	<i>NI</i>	<i>I</i>
<i>NI</i>	0	0
<i>I</i>	0	$\frac{1}{2}$

- ▶ Conditional on receiving signal *I*, the average game is:

	<i>NI</i>	<i>I</i>
<i>NI</i>	0, 0	0, $-\varepsilon$
<i>I</i>	$-\varepsilon, 0$	0, 0

- ▶ In this direct information structure, “always play *NI*” is the smallest equilibrium.
- ▶ In fact, this outcome (and any outcome close to it) is not S-implementable.

# Sequential Obedience

- ▶  $\Gamma$ : Set of sequences of distinct players
- ▶  $\Gamma_i \subset \Gamma$ : Set of sequences in which  $i$  appears
- ▶  $a(\gamma) \in A$ : Action profile of all players where players that appear  $\gamma$  play action 1
- ▶  $a_{-i}(\gamma) \in A_{-i}$ : Action profile of opponent players where players that appear before  $i$  in  $\gamma$  play action 1
- ▶  $\nu_\Gamma \in \Delta(\Gamma \times \Theta)$ : “Ordered outcome”
- ▶ Ordered outcome  $\nu_\Gamma$  induces an outcome  $\nu \in \Delta(A \times \Theta)$  by

$$\nu(a, \theta) = \sum_{\gamma \in \Gamma: a(\gamma)=a} \nu_\Gamma(\gamma, \theta).$$

## Definition 4

- ▶ Ordered outcome  $\nu_\Gamma$  satisfies **sequential obedience** if

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) \geq 0$$

for all  $i \in I$ .

- ▶ Outcome  $\nu$  satisfies sequential obedience if there exists an ordered outcome  $\nu_\Gamma$  that induces  $\nu$  and satisfies sequential obedience.

## Definition 5

- ▶ Ordered outcome  $\nu_\Gamma$  satisfies **strict sequential obedience** if

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) > 0$$

for all  $i \in I$  such that  $\nu_\Gamma(\Gamma_i \times \Theta) > 0$ .

- ▶ Outcome  $\nu$  satisfies strict sequential obedience if there exists an ordered outcome  $\nu_\Gamma$  that induces  $\nu$  and satisfies strict sequential obedience.

# Characterization

## Theorem 1

1. *If  $\nu \in SI$ , then it satisfies consistency, obedience, and strict sequential obedience.*
2. *If  $\nu$  with  $\nu(\mathbf{1}, \bar{\theta}) > 0$  satisfies consistency, obedience, and strict sequential obedience, then  $\nu \in SI$ .*

## Corollary 2

*$\nu \in \overline{SI}$  if and only if it satisfies consistency, obedience, and sequential obedience.*

## Necessity of Sequential Obedience

- ▶ Suppose that  $\nu$  is smallest equilibrium implementable.
- ▶ Let  $\mathcal{T} = ((T_i)_{i \in I}, \pi)$  be an information structure whose smallest equilibrium induces  $\nu$ .
- ▶ Starting with the smallest strategy  $\sigma_i^0(t_i) = 0$  for all  $i \in I$  and all  $t_i \in T_i$ , apply sequential best response in the order  $1, 2, \dots, |I|$ .
  - ▶  $\sigma_i^n(t_i) = 1$  if  $i \equiv n \pmod{|I|}$  and  $\sum_{t_{-i}, \theta} \pi((t_i, t_{-i}), \theta) d_i(\sigma_{-i}^{n-1}(t_{-i}), \theta) > 0$ ,
  - ▶  $\sigma_i^n(t_i) = \sigma_i^{n-1}(t_i)$  otherwise.
- ▶ By supermodularity, this process converges monotonically to the smallest equilibrium.

▶ Let

▶  $n_i(t_i) = n$  if  $\sigma_i^{n-1}(t_i) = 0$  and  $\sigma_i^n(t_i) = 1$ , and

▶  $n_i(t_i) = \infty$  if  $\sigma_i^n(t_i) = 0$  for all  $n$ .

▶  $T(\gamma)$ : Set of type profiles  $t$  such that  $n_i(t_i) = \infty$  if  $i \notin S(\gamma)$ , and  $n_{i_\ell}(t_{i_\ell}) < n_{i_m}(t_{i_m})$  if and only if  $\ell < m$

▶ Define

$$\nu_\Gamma(\gamma, \theta) = \sum_{t \in T(\gamma)} \pi(t, \theta).$$

▶  $\nu_\Gamma$  induces  $\nu$ :

$$\sum_{\gamma \in \Gamma: a(\gamma) = a} \nu_\Gamma(\gamma, \theta) = \sum_{\gamma \in \Gamma: a(\gamma) = a} \sum_{t \in T(\gamma)} \pi(t, \theta) = \sum_{t \in T: \underline{\sigma}(t) = a} \pi(t, \theta) = \nu(a, \theta).$$

- ▶ For each  $t_i \in T_i$  with  $n_i(t_i) < \infty$ ,

$$\sum_{t_{-i}, \theta} \pi((t_i, t_{-i}), \theta) d_i(\sigma_{-i}^{n_i(t_i)-1}(t_{-i}), \theta) > 0.$$

- ▶ By adding up the inequality over all such  $t_i$ , we have

$$\begin{aligned} 0 &< \sum_{t_i: n_i(t_i) < \infty} \sum_{t_{-i}, \theta} \pi(t, \theta) d_i(\sigma_{-i}^{n_i(t_i)-1}(t_{-i}), \theta) \\ &= \sum_{\gamma \in \Gamma_i, \theta} \sum_{t \in T(\gamma)} \pi(t, \theta) d_i(a_{-i}(\gamma), \theta) \\ &= \sum_{\gamma \in \Gamma_i, \theta} \nu_{\Gamma}(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) \end{aligned}$$

for any  $i \in I$  such that  $\nu_{\Gamma}(\Gamma_i \times \Theta) > 0$ .

- ▶ Thus, strict sequential obedience is satisfied.



## Sufficiency of Sequential Obedience

- ▶ Let  $\nu_\Gamma \in \Delta(\Gamma \times \Theta)$  satisfy strict sequential obedience.
- ▶ We construct an information structure as follows.
  - ▶  $T_i = \{1, 2, \dots\} \cup \{\infty\}$
  - ▶ By the assumption  $\nu(\mathbf{1}, \bar{\theta}) > 0$ ,  
 $\nu_\Gamma(\bar{\gamma}, \bar{\theta}) > 0$  for some sequence  $\bar{\gamma}$  of all players.  
Take  $\varepsilon > 0$  such that  $\varepsilon < \nu_\Gamma(\bar{\gamma}, \bar{\theta})$ .
  - ▶  $m$  drawn from  $\mathbb{Z}_+$  according to the distribution  $\eta(1 - \eta)^m$ ,  
where  $0 < \eta \ll \varepsilon$ .
  - ▶  $\gamma$  drawn from  $\Gamma$  according to  $\nu_\Gamma$ .
  - ▶ Player  $i$  receives signal  $t_i$  given by

$$t_i = \begin{cases} m + (\text{ranking of } i \text{ in } \gamma) & \text{if } \gamma \in \Gamma_i \\ \infty & \text{otherwise.} \end{cases}$$

- ▶ To initiate contagion, re-arrange probabilities:
  - ▶ Replace  $\nu_{\Gamma}(\bar{\gamma}, \bar{\theta})$  with  $\nu_{\Gamma}(\bar{\gamma}, \bar{\theta}) - \varepsilon$ .
  - ▶ Allocate  $\frac{\varepsilon}{|I|-1}$  to  $(t, \bar{\theta})$  such that  $1 \leq t_1 = \dots = t_{|I|} \leq |I| - 1$ .
  - ▶ Since  $\eta \ll \varepsilon$ , types  $t_i \in \{1, \dots, |I| - 1\}$  will assign high probability to  $\bar{\theta}$ .

- ▶ Show by induction that action 1 is the unique action surviving iterated deletion of dominated strategies for all types  $t_i < \infty$ .

- ▶ Initialization step:

If  $t_i \in \{1, \dots, |I| - 1\}$ , the player assigns high probability to  $\theta = \bar{\theta}$ , and by Dominance State, action 1 is a dominant action.

- ▶ Induction step:

For  $\tau \geq |I|$ , Suppose all types  $t_i \leq \tau - 1$  play action 1.

Then type  $t_i = \tau$  knows that all players before him in the realized sequence play action 1, so his payoff to 1 is at least

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_{\Gamma}(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) \times (\text{constant}) > 0 \quad \text{as } \eta \approx 0,$$

where the inequality is by strict sequential obedience.

## Two-Player Two-State Example (Symmetric Payoffs)

	<i>B</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		-1	$-1 + \varepsilon$

	<i>G</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		$x$	$x + \varepsilon$

- ▶ S-implementable outcome:

	<i>B</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		$\frac{1-x-\varepsilon}{2-\varepsilon} + \delta$	0
<i>I</i>		0	$\frac{2x+\varepsilon}{2(2-\varepsilon)} - \delta$

	<i>G</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		0	$\frac{1}{2}$

- ▶ The limit as  $\delta \rightarrow 0$  attains the supremum when the objective is to maximize the expected number of players who invest.

	<i>B</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		-1	-1 + $\varepsilon$

	<i>G</i>	<i>NI</i>	<i>I</i>
<i>NI</i>		0	0
<i>I</i>		$x$	$x + \varepsilon$

- By symmetry, consider the symmetric ordered outcome:

		<i>B</i>	<i>G</i>
$\emptyset$		$\frac{1}{2} - 2p$	0
12		$p$	$\frac{1}{4}$
21		$p$	$\frac{1}{4}$

- Determine  $p$  such that sequential obedience is satisfied with equality.

- ▶ In the information structure constructed in the sufficiency proof, if the players receive  $t_i = \infty$ , then they know that  $\theta = B$  and play  $NI$  as a dominant action.
- ▶ Conditional on not receiving  $t_i = \infty$ , the average game as  $\delta \rightarrow 0$  is:

	$NI$	$I$
$NI$	$0, 0$	$0, -\frac{\epsilon}{2}$
$I$	$-\frac{\epsilon}{2}, 0$	$\frac{\epsilon}{2}, \frac{\epsilon}{2}$

$(I, I)$ : risk-dominant (strictly risk-dominant with  $\delta > 0$ )

- ▶ Then signals as in the Email game are sent, using the dominance state  $\bar{\theta} = G$  as “crazy types”.

# Dual Characterization of Sequential Obedience

► Recall:

$\nu \in \Delta(A \times \Theta)$  satisfies sequential obedience if there exists  $\nu_\Gamma \in \Delta(\Gamma \times \Theta)$  that induces  $\nu$  and satisfies

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) \geq 0 \text{ for all } i \in I. \quad (\#\#)$$

## Proposition 3

*$\nu$  satisfies sequential obedience if and only if*

$$\sum_{a \in A, \theta \in \Theta} \nu(a, \theta) \max_{\gamma: \bar{a}(\gamma) = a} \sum_{i \in S(a)} \lambda_i d_i(a_{-i}(\gamma), \theta) \geq 0$$

*for all  $(\lambda_i)_{i \in I} \geq 0$ . (#)*

## Proof

- ▶ Fix  $\nu \in \Delta(A \times \Theta)$ .
- ▶ Let  $N_\Gamma(\nu) = \{\nu_\Gamma \in \Delta(\Gamma \times \Theta) \mid \sum_{\gamma: \bar{a}(\gamma)=a} \nu_\Gamma(\gamma, \theta) = \nu(a, \theta)\}$   
and  $\Lambda(\nu) = \{\lambda \in \Delta(I) \mid \sum_{i \in I(\nu)} \lambda_i = 1\}$ .  
(Both are convex and compact.)
- ▶ For  $\nu_\Gamma \in N_\Gamma(\nu)$  and  $\lambda \in \Lambda(\nu)$ , let

$$\begin{aligned} D(\nu_\Gamma, \lambda) &= \sum_{i \in I} \lambda_i \sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) \\ &= \sum_{\gamma \in \Gamma, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) \sum_{i \in S(\gamma)} \lambda_i d_i(a_{-i}(\gamma), \theta) \\ &= \sum_{a \in A, \theta \in \Theta} \sum_{\gamma: \bar{a}(\gamma)=a} \nu_\Gamma(\gamma, \theta) \sum_{i \in S(a)} \lambda_i d_i(a_{-i}(\gamma), \theta). \end{aligned}$$

(Linear in each of  $\nu_\Gamma$  and  $\lambda$ .)



- ▶ By the Minimax Theorem,  $D$  has a value  $D^*$ :

$$\min_{\lambda \in \Lambda(\nu)} \max_{\nu_\Gamma \in N_\Gamma(\nu)} D(\nu_\Gamma, \lambda) = D^* = \max_{\nu_\Gamma \in N_\Gamma(\nu)} \min_{\lambda \in \Lambda(\nu)} D(\nu_\Gamma, \lambda).$$

- ▶  $\nu$  satisfies sequential obedience

$$\iff \exists \nu_\Gamma \in N_\Gamma(\nu) \forall \lambda \in \Lambda(\nu): D(\nu_\Gamma, \lambda) \geq 0$$

$$\iff D^* = \max_{\nu_\Gamma \in N_\Gamma(\nu)} \min_{\lambda \in \Lambda(\nu)} D(\nu_\Gamma, \lambda) \geq 0$$

- ▶ (LHS of (#)) =  $\max_{\nu_\Gamma \in N_\Gamma(\nu)} D(\nu_\Gamma, \lambda)$  for each  $\lambda \in \Lambda(\nu)$

Hence,

$$\text{(#)} \text{ holds } \iff D^* = \min_{\lambda \in \Lambda(\nu)} \max_{\nu_\Gamma \in N_\Gamma(\nu)} D(\nu_\Gamma, \lambda) \geq 0$$

# Sequential Obedience in Potential Games

- ▶ In potential games,  
the dual condition ( $\#$ ) (hence sequential obedience) is  
equivalent to a simpler *coalitional obedience* condition.

# Potential Games

## Definition 6

The game is a potential game if there exists  $\Phi: A \times \Theta \rightarrow \mathbb{R}$  such that

$$d_i(a_{-i}, \theta) = \Phi(1, a_{-i}, \theta) - \Phi(0, a_{-i}, \theta).$$

- ▶ For each  $\nu \in \Delta(A \times \Theta)$ , we define a potential for that outcome:

$$\Phi_\nu(a) = \sum_{a', \theta} \nu(a', \theta) \Phi(a \wedge a', \theta)$$

where  $b = a \wedge a'$  is the action profile such that  $b_i = 1$  if and only if  $a_i = a'_i = 1$ .

# Potential Games

- ▶ For simplicity, we focus on outcomes  $\nu$  such that  $\nu(\{\mathbf{1}\} \times \Theta) > 0$ .

## Definition 7

Outcome  $\nu$  satisfies *coalitional obedience* if

$$\Phi_\nu(\mathbf{1}) \geq \Phi_\nu(a)$$

for all  $a \in A$ .

## Proposition 4

*In a potential game, an outcome satisfies sequential obedience if and only if it satisfies coalitional obedience.*

- ▶ Show that coalitional obedience is equivalent to the dual condition ( $\sharp$ ) of sequential obedience.

# Convex Potential

- ▶ Normalize:  $\Phi(\mathbf{0}, \theta) = 0$  for all  $\theta$ .
- ▶ Denote  $n(a) = |\{i \in I \mid a_i = 1\}|$ .

## Definition 8

The potential  $\Phi$  satisfies *convexity* if

$$\Phi(a, \theta) \leq \frac{n(a)}{|I|} \Phi(\mathbf{1}, \theta) \quad \left( = \left( 1 - \frac{n(a)}{|I|} \right) \Phi(\mathbf{0}, \theta) + \frac{n(a)}{|I|} \Phi(\mathbf{1}, \theta) \right)$$

for all  $\theta$ .

- ▶ Because of supermodularity, this is automatically satisfied if  $\Phi$  is symmetric.
- ▶ The potential is convex if and only if the game is not too asymmetric.

# Investment Game

- ▶  $\Theta = \{1, \dots, |\Theta|\}$
- ▶  $d_i(a_{-i}, \theta) = R(\theta) + h_{n(a_{-i})+1} - c_i$

- ▶  $h_k$ : increasing in  $k$
- ▶  $R(\theta)$ : strictly increasing in  $\theta$
- ▶  $R(|\Theta|) + h_1 > c_i$  for all  $i \in I$

Dominant state is satisfied with  $\bar{\theta} = |\Theta|$

- ▶  $c_1 \leq c_2 \leq \dots \leq c_{|I|}$
- ▶ This game has a potential:

$$\Phi(a, \theta) = R(\theta)n(a) + \sum_{k=1}^{n(a)} h_k - \sum_{i \in S(a)} c_i.$$

- ▶  $\Phi$  satisfies convexity if and only if

$$\frac{1}{\ell} \sum_{k=1}^{\ell} (h_k - c_k) \leq \frac{1}{|I|} \sum_{k=1}^{|I|} (h_k - c_k)$$

for any  $\ell = 1, \dots, |I| - 1$ .

- ▶ In particular, a sufficient condition for convexity is:

$$h_k - c_k \leq h_{k+1} - c_{k+1}$$

for any  $k = 1, \dots, |I| - 1$ .

# Regime Change Game

- ▶  $\Theta = \{1, \dots, |\Theta|\}$
- ▶  $d_i(a_{-i}, \theta) = \begin{cases} c_i & \text{if } n(a_{-i}) \geq |I| - k(\theta) \\ c_i - 1 & \text{if } n(a_{-i}) < |I| - k(\theta) \end{cases}$ 
  - ▶  $0 < c_i < 1$
  - ▶  $k: \Theta \rightarrow \mathbb{N}$ : strictly increasing,  $k(1) \geq 1$
  - ▶  $k(|\Theta|) = |I|$ 

Dominant state is satisfied with  $\bar{\theta} = |\Theta|$
- ▶ Action 0: to attack the regime  
Action 1: to abstain from attacking
- ▶ The regime collapses if  $\#(\text{action 0 players}) > k(\theta)$   
 $\iff \#(\text{action 1 players}) < |I| - k(\theta)$



# Regime Change Game

- ▶ This game has a potential:

$$\Phi(a, \theta) = \begin{cases} \sum_{i \in S(a)} c_i - (|I| - k(\theta)) & \text{if } n(a) \geq |I| - k(\theta), \\ \sum_{i \in S(a)} c_i - n(a) & \text{if } n(a) < |I| - k(\theta). \end{cases}$$

- ▶  $\Phi$  satisfies convexity if and only if  $c_1 = \dots = c_{|I|}$ .

# Grand Coalitional Obedience and Perfect Coordination

## Definition 9

Outcome  $\nu$  satisfies *grand coalitional obedience* if

$$\Phi_\nu(\mathbf{1}) \geq \Phi_\nu(\mathbf{0}) = 0,$$

or equivalently,

$$\sum_{a \in A, \theta \in \Theta} \nu(a, \theta) \Phi(a, \theta) \geq 0.$$

## Definition 10

Outcome  $\nu$  satisfies *perfect coordination* if  $\nu(a, \theta) > 0$  only for  $a \in \{\mathbf{0}, \mathbf{1}\}$ .

## Proposition 5

*Suppose that the potential satisfies convexity.*

*A perfectly coordinated outcome satisfies sequential obedience if and only if it satisfies grand coalitional obedience.*

# Information Design with Adversarial Equilibrium Selection

- ▶ Information designer's objective function:  $V : A \times \Theta \rightarrow \mathbb{R}$
- ▶  $V(a, \theta)$ : increasing in  $a$
- ▶ Normalization:  $V(\mathbf{0}, \theta) = 0$  for all  $\theta$
- ▶ Optimal information design problem with adversarial equilibrium selection:

$$\begin{aligned} & \sup_{\mathcal{T}} \min_{\sigma \in E(\mathcal{T})} \sum_{t \in T, \theta \in \Theta} \pi(t, \theta) V(\sigma(t), \theta) \\ &= \sup_{\mathcal{T}} \sum_{t \in T, \theta \in \Theta} \pi(t, \theta) V(\underline{\sigma}(t), \theta). \end{aligned}$$

- ▶ This is equivalent to

$$\sup_{\nu \in SI} \sum_{a \in A, \theta \in \Theta} \nu(a, \theta) V(a, \theta) = \max_{\nu \in \overline{SI}} \sum_{a \in A, \theta \in \Theta} \nu(a, \theta) V(a, \theta).$$

# Restricted Convexity

## Definition 11

Designer's objective  $V$  satisfies *restricted convexity* with respect to potential  $\Phi$  if

$$V(a, \theta) \leq \frac{n(a)}{|I|} V(\mathbf{1}, \theta)$$

whenever  $\Phi(a, \theta) > \Phi(\mathbf{1}, \theta)$ .

## Special cases of interest

- ▶ Linear preferences

$$V(a, \theta) = n(a)$$

- ▶ Full coordination preferences

$$V(a, \theta) = \begin{cases} 1 & \text{if } a = \mathbf{1} \\ 0 & \text{otherwise} \end{cases}$$

► Regime change preferences:

► Potential

$$\Phi(a, \theta) = \begin{cases} \sum_{i \in S(a)} c_i - (|I| - k(\theta)) & \text{if } n(a) \geq |I| - k(\theta) \\ \sum_{i \in S(a)} c_i - n(a) & \text{if } n(a) < |I| - k(\theta) \end{cases}$$

►  $\Phi(a, \theta) > \Phi(\mathbf{1}, \theta)$  holds only when  $n(a) < |I| - k(\theta)$ .

► The objective

$$V(a, \theta) = \begin{cases} 1 & \text{if } n(a) \geq |I| - k(\theta) \\ 0 & \text{if } n(a) < |I| - k(\theta) \end{cases}$$

satisfies restricted convexity with respect to  $\Phi$ .

# Perfect Coordination Solution

## Theorem 2

*Suppose that  $\Phi$  satisfies convexity and  $V$  satisfies restricted convexity with respect to  $\Phi$ .*

*Then there exists an optimal outcome of the adversarial information design problem that satisfies perfect coordination.*

# Proof

- ▶ Consider the problem

$$\max_{(\nu(\mathbf{1}, \theta))_{\theta \in \Theta}} \sum_{\theta \in \Theta} \nu(\mathbf{1}, \theta) V(\mathbf{1}, \theta)$$

with respect to perfect coordination outcomes,  
subject to

- ▶ grand coalitional obedience:  
$$\sum_{a \in A, \theta \in \Theta} \nu(a, \theta) \Phi(a, \theta) \geq 0,$$
- ▶ consistency:  
$$0 \leq \nu(\mathbf{1}, \theta) \leq \mu(\theta) \quad (\theta \in \Theta).$$



- ▶ Easy to characterize the solution to this problem:
  - ▶ Relabel the states as  $\Theta = \{1, \dots, |\Theta|\}$  in such a way that  $\frac{\Phi(\mathbf{1}, \theta)}{V(\mathbf{1}, \theta)}$  is increasing in  $\theta$ .
  - ▶ Ignoring integer issues, find  $\theta^*$  that solves

$$\sum_{\theta > \theta^*} \mu(\theta) \Phi(\mathbf{1}, \theta) = 0 \quad \left( = \sum_{\theta > \theta^*} \mu(\theta) \Phi(\mathbf{0}, \theta) \right).$$

- ▶ Let

$$\nu^*(a, \theta) = \begin{cases} \mu(\theta) & \text{if } a = \mathbf{1} \text{ and } \theta > \theta^*, \\ \mu(\theta) & \text{if } a = \mathbf{0} \text{ and } \theta \leq \theta^*, \\ 0 & \text{otherwise.} \end{cases}$$

- ▶ We want to show that  $\nu^*$  is an optimal outcome of the adversarial information design problem.
- ▶ Take any  $\nu \in \overline{SI}$ .
- ▶ Show that there exists a perfect coordination outcome  $\nu'$  satisfying consistency such that
  - ▶ grand coalitional obedience is satisfied (by convexity of  $\Phi$ ), and
  - ▶  $\sum_{a,\theta} \nu'(a, \theta)V(a, \theta) \geq \sum_{a,\theta} \nu(a, \theta)V(a, \theta)$   
(by restricted convexity of  $V$ ).

If  $\nu(a, \theta) > 0$  for  $a \neq \mathbf{0}, \mathbf{1}$ , split  $\nu(a, \theta)$  to  $(\mathbf{0}, \theta)$  and  $(\mathbf{1}, \theta)$  appropriately.