

Full Implementation in Binary-Action Supermodular Games

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Game Theory I

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Paper

- ▶ Morris, S., D. Oyama, and S. Takahashi (2020).
“Implementation via Information Design in Binary-Action Supermodular Games.”

Base Game

- ▶ $I = \{1, \dots, |I|\}$: Set of players
- ▶ $A_i = \{0, 1\}$: Binary action set for i ($A = A_1 \times \dots \times A_{|I|}$)
- ▶ Θ : Finite set of states
- ▶ $\mu \in \Delta(\Theta)$: Probability distribution over Θ
Assume full support: $\mu(\theta) > 0$ for all $\theta \in \Theta$

- ▶ $u_i: A \times \Theta \rightarrow \mathbb{R}$: i 's payoff function, supermodular:

$$d_i(a_{-i}, \theta) = u_i(1, a_{-i}, \theta) - u_i(0, a_{-i}, \theta)$$

increasing in a_{-i}

- ▶ **Two-sided** dominance states:

There exist $\bar{\theta}, \underline{\theta} \in \Theta$ such that $d_i(\mathbf{0}_{-i}, \bar{\theta}) > 0$ and $d_i(\mathbf{1}_{-i}, \underline{\theta}) < 0$ for all $i \in I$.

Information Structures

- ▶ T_i : Set of types of player i (finite or countably infinite)

$$(T = T_1 \times \cdots \times T_{|I|})$$

- ▶ $\pi \in \Delta(T \times \Theta)$: Common prior, consistent with μ :

$$\sum_t \pi(t, \theta) = \mu(\theta)$$

for all $\theta \in \Theta$.

- ▶ Together with the base game, an information structure $\mathcal{T} = ((T_i)_{i \in I}, \pi)$ defines an incomplete information game:
 - ▶ $\sigma_i: T_i \rightarrow \Delta(A_i)$: Strategy of player i
 - ▶ Bayes Nash equilibrium (BNE) is defined as usual.
 - ▶ $E(\mathcal{T})$: Set of BNEs.
 - ▶ $\underline{\sigma} = (\underline{\sigma}_i)_{i \in I}$: Smallest (pure-strategy) BNE
- ▶ The *outcome* $\nu \in \Delta(A \times \Theta)$ induced by information structure \mathcal{T} and strategy profile σ :

$$\nu(a, \theta) = \sum_t \pi(t, \theta) \prod_{i \in I} \sigma_i(t_i)(a_i).$$

- ▶ Outcome ν satisfies *consistency* if $\sum_{a \in A} \nu(a, \theta) = \mu(\theta)$ for all $\theta \in \Theta$.

Partial Implementation

Definition 1

Outcome ν is *partially implementable* if there exist an information structure \mathcal{T} and an equilibrium $\sigma \in E(\mathcal{T})$ that induce ν .

Proposition 1

Outcome ν is partially implementable if and only if it is a Bayes correlated equilibrium.

- ▶ *BCE*: Set of partially implementable outcomes, or equivalently Bayes correlated equilibria

Smallest Equilibrium Implementation (S-Implementation)

Definition 2

Outcome ν is **S-implementable** if there exists an information structure \mathcal{T} such that $(\mathcal{T}, \underline{\sigma})$ induces ν .

Definition 3

Outcome ν is **fully implementable** if there exists an information structure \mathcal{T} such that (\mathcal{T}, σ) induces ν for all $\sigma \in E(\mathcal{T})$.

- ▶ SI : Set of S-implementable outcomes
- ▶ FI : Set of fully implementable outcomes
- ▶ $FI \subset SI \subset BCE$

Sequential Obedience

- ▶ Γ : Set of sequences of distinct players
- ▶ $\Gamma_i \subset \Gamma$: Set of sequences in which i appears
- ▶ $a(\gamma) \in A$: Action profile of all players where players that appear γ play action 1
- ▶ $a_{-i}(\gamma) \in A_{-i}$: Action profile of opponent players where players that appear before i in γ play action 1
- ▶ $\nu_\Gamma \in \Delta(\Gamma \times \Theta)$: “Ordered outcome”
- ▶ Ordered outcome ν_Γ induces an outcome $\nu \in \Delta(A \times \Theta)$ by

$$\nu(a, \theta) = \sum_{\gamma \in \Gamma: a(\gamma)=a} \nu_\Gamma(\gamma, \theta).$$

Definition 4

- ▶ Ordered outcome ν_Γ satisfies **sequential obedience** if

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) \geq 0$$

for all $i \in I$.

- ▶ Outcome ν satisfies sequential obedience if there exists an ordered outcome ν_Γ that induces ν and satisfies sequential obedience.

Definition 5

- ▶ Ordered outcome ν_Γ satisfies **strict sequential obedience** if

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma(\gamma, \theta) d_i(a_{-i}(\gamma), \theta) > 0$$

for all $i \in I$ such that $\nu_\Gamma(\Gamma_i \times \Theta) > 0$.

- ▶ Outcome ν satisfies strict sequential obedience if there exists an ordered outcome ν_Γ that induces ν and satisfies strict sequential obedience.

Reverse Sequential Obedience

- ▶ $a^0(\gamma) \in A$: Action profile of all players where players that appear γ play action 0
- ▶ $a_{-i}^0(\gamma) \in A_{-i}$: Action profile of opponent players where players that appear before i in γ play action 0
- ▶ Ordered outcome $\nu_{\Gamma}^0 \in \Delta(\Gamma \times \Theta)$ *reverse induces* an outcome $\nu \in \Delta(A \times \Theta)$ by

$$\nu(a, \theta) = \sum_{\gamma \in \Gamma: a^0(\gamma) = a} \nu_{\Gamma}^0(\gamma, \theta).$$

Definition 6

- ▶ Ordered outcome ν_{Γ}^0 satisfies **reverse sequential obedience** if

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_{\Gamma}^0(\gamma, \theta) d_i(a_{-i}^0(\gamma), \theta) \leq 0$$

for all $i \in I$.

- ▶ Outcome ν satisfies sequential obedience if there exists an ordered outcome ν_{Γ}^0 that reverse induces ν and satisfies reverse sequential obedience.

Definition 7

- ▶ Ordered outcome ν_Γ satisfies **strict reverse sequential obedience** if

$$\sum_{\gamma \in \Gamma_i, \theta \in \Theta} \nu_\Gamma^0(\gamma, \theta) d_i(a_{-i}^0(\gamma), \theta) < 0$$

for all $i \in I$ such that $\nu_\Gamma^0(\Gamma_i \times \Theta) > 0$.

- ▶ Outcome ν satisfies sequential obedience if there exists an ordered outcome ν_Γ^0 that reverse induces ν and satisfies strict reverse sequential obedience.

Characterization

Theorem 1

1. *If $\nu \in FI$, then it satisfies consistency, strict sequential obedience, and strict reverse sequential obedience.*
2. *If ν with $\nu(\mathbf{1}, \bar{\theta}) > 0$ and $\nu(\mathbf{0}, \underline{\theta}) > 0$ satisfies consistency, strict sequential obedience, and strict reverse sequential obedience, then $\nu \in FI$.*

► Part 1:

Fully implementable \Rightarrow S-implementable and L-implementable

Apply the characterization of S-implementability

Part 2

- ▶ Let ν satisfy consistency, strict sequential obedience with ν_Γ , and strict reverse sequential obedience with ν_Γ^0 .
- ▶ Given $\theta \in \Theta$, draw $a \in A$ according to ν ;
and draw $\gamma^+ \in \Pi(S(a))$ and $\gamma^- \in \Pi(I \setminus S(a))$ according to ν_Γ and ν_Γ^0 , respectively.
- ▶ Draw $m \in \mathbb{Z}_+$ according to $\eta(1 - \eta)^m$.
- ▶ Each player receives a signal $t_i = (s_i, a_i)$ where

$$s_i = \begin{cases} s_i = m + (\text{ranking of } i \text{ in } \gamma^+) & \text{if } a_i = 1, \\ s_i = m + (\text{ranking of } i \text{ in } \gamma^-) & \text{if } a_i = 0. \end{cases}$$

- ▶ Re-arrange probabilities so that the player believes with high probability that the state is $\bar{\theta}$ (resp. $\underline{\theta}$) if $s_i \in \{1, \dots, |I|\}$ and $\theta = \bar{\theta}$ (resp. $\theta = \underline{\theta}$).
- ▶ Then, a similar argument as in the sufficiency proof for S-implementability shows that the player with signal (t_i, a_i) with $a_i = 1$ (resp. $a_i = 0$) plays action 1 (resp. action 0) as a unique rationalizable action.

SO/Reverse SO in Complete Information Games

- ▶ $\mathbf{f} = (f_i)_{i \in I}$: Complete information BAS game
- ▶ Endow $\Delta(A)$ with the first-order stochastic dominance order.
For $\xi, \hat{\xi} \in \Delta(A)$, $\hat{\xi}$ first-order stochastically dominates ξ if
$$\sum_{a \in B} \hat{\xi}(a) \geq \sum_{a \in B} \xi(a)$$
 for all upper sets $B \subset A$
(i.e., sets B such that $a' \in B$ whenever $a \in B$ and $a' \geq a$).
- ▶ $\bar{X} \subset \Delta(A)$:
Set of outcomes that satisfy sequential obedience in \mathbf{f}
 $\bar{X}^0 \subset \Delta(A)$:
Set of outcomes that satisfy reverse sequential obedience in \mathbf{f}

Proposition 2 (Oyama and Takahashi (2019), Lemma 2(2))

1. \bar{X} has a largest element, which is degenerate on some action profile \bar{a} .
2. \bar{X}^0 has a smallest element, which is degenerate on some action profile \underline{a} .

Proposition 3 (MOT20, Proposition B.2)

1. \bar{a} satisfies strict reverse sequential obedience.
2. \underline{a} satisfies strict sequential obedience.

In particular, $\underline{a} \leq \bar{a}$.

► By duality

S-Implementation versus Full Implementation

- ▶ Go back to BAS game $(d_i)_{i \in I}$, with the two-sided dominance states assumption.

Lemma 4

If $\nu \in \Delta(A \times \Theta)$ satisfies

- ▶ consistency,
- ▶ strict sequential obedience, and
- ▶ $\nu(\mathbf{1}, \bar{\theta}) > 0$ and $\nu(\mathbf{0}, \underline{\theta}) > 0$,

then there exists $\hat{\nu} \in \Delta(A \times \Theta)$ that

- ▶ first-order stochastically dominates ν and
- ▶ satisfies consistency,
- ▶ strict sequential obedience, and
- ▶ strict reverse sequential obedience, and
- ▶ $\hat{\nu}(\mathbf{1}, \bar{\theta}) > 0$ and $\hat{\nu}(\mathbf{0}, \underline{\theta}) > 0$.

Proposition 5

For any $\nu \in \overline{SI}$, there exists $\hat{\nu} \in \overline{FI}$ that first-order stochastically dominates ν .

- ▶ In particular, $FI \neq \emptyset$.

Proposition 6

Suppose that the objective function $V(a, \theta)$ is nondecreasing in a . Then optimal information design with S -implementation is equivalent to that with full implementation.