## 9. Envelope Theorem

Daisuke Oyama

Mathematics II

May 16, 2025

# Parameterized Optimization (with Constant Constraints) Let $X \subset \mathbb{R}^N$ be a nonempty set, $A \subset \mathbb{R}^S$ a nonempty open set. For $f: X \times A \to \mathbb{R}$ , consider the optimal value function

$$v(q) = \sup_{x \in X} f(x, q),$$

and the optimal solution correspondence

$$X^*(q) = \{ x \in X \mid f(x,q) = v(q) \}.$$

We assume that  $X^*(q) \neq \emptyset$  for all  $q \in A$ .

We want to investigate the marginal effects of changes in q on the value v(q).

Formally, the envelope theorem gives

- 1. a sufficient condition under which  $\boldsymbol{v}$  is differentiable, and
- 2. a formula for the derivative ("envelope formula").

# Outline

Envelope formula is best interpreted through FOC under the differentiability of the solution function (or selection) and the differentiability of f in (x, q),

while these assumptions are irrelevant for the differentiability of  $\boldsymbol{v}$  and deriving the formula.

If we directly assume the differentiability of v, deriving the envelope formula is just a straightforward routine.

Differentiability of v is the real content of envelope theorem.

- Non-differentiability of v is a typical case when there are more than one solutions.
- Provide a sufficient condition under which uniqueness of solution implies differentiability of v,

with applications for the differentiability of support function (or profit function), indirect utility function, and expenditure function.

# Main Reference

D. Oyama and T. Takenawa, "On the (Non-)Differentiability of the Optimal Value Function When the Optimal Solution Is Unique," *Journal of Mathematical Economics* 76, 21-32 (2018).

# Envelope Theorem via FOC

## Proposition 9.1

Let  $x(\cdot)$  be a selection of  $X^*$ , i.e., a function such that  $x(q) \in X^*(q)$  for all  $q \in A$ . Assume that

1. f is differentiable on  $Int X \times A$ , and

2.  $x(\bar{q}) \in \text{Int } X$ , and  $x(\cdot)$  is differentiable at  $\bar{q}$ . Then, v is differentiable at  $\bar{q}$ , and

$$\frac{\partial v}{\partial q_s}(\bar{q}) = \frac{\partial f}{\partial q_s}(x(\bar{q}), \bar{q}), \qquad s = 1, \dots, S.$$

▶ By the assumptions, v(q) = f(x(q), q) is differentiable at  $\bar{q}$ .

We have

$$\begin{split} \frac{\partial v}{\partial q_s}(\bar{q}) &= \frac{\partial}{\partial q_s} f(x(q), q) \Big|_{q = \bar{q}} \\ &= \sum_n \underbrace{\frac{\partial f}{\partial x_n}(x(\bar{q}), \bar{q})}_{= 0 \text{ by FOC}} \frac{\partial x_n}{\partial q_s}(\bar{q}) + \frac{\partial f}{\partial q_s}(x(\bar{q}), \bar{q}) \\ &= \frac{\partial f}{\partial q_s}(x(\bar{q}), \bar{q}). \end{split}$$

- The change in the solution caused by the change in q has no first-order effect on the value;
- the only effect is the direct effect.

A Sufficient Condition for the Differentiability of  $x(\cdot)$ 

## Proposition 9.2

Assume that

- 1. X is compact and f is continuous,
- 2. for each  $q \in A$ ,  $X^*(q) = \{x(q)\} \subset \operatorname{Int} X$ ,

## 3. $\nabla_x f$ exists and is continuously differentiable on $\operatorname{Int} X \times A$ , and

4.  $|D_x^2 f(x(\bar{q}), \bar{q})| \neq 0.$ 

Then,  $x(\cdot)$  is continuously differentiable on a neighborhood of  $\bar{q}$ .

By assumptions, x(·) is continuous by the Theorem of Maximum.

• By the FOC, 
$$\nabla_x f(x(q), q) = 0$$
 for all  $q \in A$ .

▶ By assumptions,  $\nabla_x f(x,q) = 0$  is uniquely solved locally as  $x = \eta(q)$  and  $\eta$  is continuously differentiable by the Implicit Function Theorem.

I.e., there exist open neighborhoods U and V of  $x(\bar{q})$  and  $\bar{q}$ , respectively, such that  $\nabla_x f(x,q) = 0$  if and only if  $x = \eta(q)$ .

- By the continuity of  $x(\cdot)$ , there exists an open neighborhood  $V' \subset V$  of  $\bar{q}$  such that  $x(q) \in U$  for all  $q \in V'$ .
- ▶ By the FOC  $\nabla_x f(x(q),q) = 0$ , it follows that  $x(q) = \eta(q)$  for all  $q \in V'$ .

# Envelope Formula

If we directly assume the differentiability of the value function v, neither the differentiability of f(x,q) in x nor that of x(q) in q is needed in deriving the envelope formula.

## Proposition 9.3

Assume that

1. for all  $x \in X$ ,  $f(x, \cdot)$  is differentiable at  $\bar{q}$ , and

2. v is differentiable at  $\bar{q}$ . Then, for any  $\bar{x} \in X^*(\bar{q})$ ,

$$\frac{\partial v}{\partial q_s}(\bar{q}) = \frac{\partial f}{\partial q_s}(\bar{x}, \bar{q}), \qquad s = 1, \dots, S.$$

- Fix any  $\bar{x} \in X^*(\bar{q})$ .
- Define the function

$$g(q) = f(\bar{x}, q) - v(q).$$

By assumption, g is differentiable at  $\bar{q}$ .

- By definition,
  - $g(q) \le 0$  for all  $q \in A$ , and •  $g(\bar{q}) = 0$ .

• Thus, g is maximized at  $\bar{q}$ , so that by FOC we have

$$0 = \frac{\partial g}{\partial q_s}(\bar{q}) = \frac{\partial f}{\partial q_s}(\bar{x},\bar{q}) - \frac{\partial v}{\partial q_s}(\bar{q}).$$

## Example: Non-Differentiable Value Function

Consider

$$f(x,q) = -\frac{1}{4}x^4 - \frac{q}{3}x^3 + \frac{1}{2}x^2 + qx - \frac{1}{4}, \quad q \in [-1,1],$$

where  $f_x(x,q) = -(x+1)(x+q)(x-1)$ .

Then we have

$$v(q) = \frac{2}{3}|q|, \quad X^*(q) = \begin{cases} \{-1\} & \text{if } q < 0, \\ \{-1,1\} & \text{if } q = 0, \\ \{1\} & \text{if } q > 0. \end{cases}$$

• At q = 0, v is not differentiable, and

there are two optimal solutions.

A Sufficient Condition for Differentiability of v

## Proposition 9.4

Assume that

- 1.  $X^*$  has a selection  $x(\cdot)$  continuous at  $\bar{q}$ , and
- 2. for all  $x \in X$ ,  $f(x, \cdot)$  is differentiable, and  $\nabla_q f$  is continuous in (x, q).

Then v is differentiable at  $\bar{q}$  with

$$\frac{\partial v}{\partial q_s}(\bar{q}) = \frac{\partial f}{\partial q_s}(x(\bar{q}), \bar{q}), \qquad s = 1, \dots, S.$$

Proof See: Oyama and Takenawa, Proposition A.1.

#### Corollary 9.5

Assume that

- 1.  $X^*$  is upper semi-continuous with  $X^*(q) \neq \emptyset$  for all  $q \in A$ ,
- 2.  $X^*(\bar{q}) = \{\bar{x}\}$ , and
- 3. for all  $x \in X$ ,  $f(x, \cdot)$  is differentiable, and  $\nabla_q f$  is continuous in (x, q).

Then v is differentiable at  $\bar{q}$  with

$$\frac{\partial v}{\partial q_s}(\bar{q}) = \frac{\partial f}{\partial q_s}(\bar{x}, \bar{q}), \qquad s = 1, \dots, S.$$

- Assumptions 1 and 2 imply that any selection of X\* is continuous at q.
- Thus the conclusion follows from Proposition 9.4.

#### Remark

► A sufficient condition for Assumption 1 is that X is compact and f is continuous, due to the Theorem of the Maximum.

# Example: Non-Differentiable Value Function

- Even if an optimal solution is unique, the value function may not be differentiable.
- ▶ In fact, there exists a continuous function  $f: X \times A \to \mathbb{R}$  such that
  - 1.  $X^*(q)$  is a singleton for all q and is continuous in q (as a single-valued function), and
  - 2. f is differentiable in q,

but v is not differentiable at some q.

See: Oyama and Takenawa, Example 2.1.

# Differentiability of the Support Function

For  $K\subset \mathbb{R}^N, \, K\neq \emptyset,$  and  $p\in \mathbb{R}^N,$  consider the support function of K,

$$\pi_K(p) = \sup_{x \in K} p \cdot x,$$

and the optimal solution correspondence,

$$S_K(p) = \{ x \in \mathbb{R}^N \mid x \in K, \ \pi_K(p) = p \cdot x \}.$$

If K is the production set of a firm,  $\pi_K$  is the profit function and  $S_K$  is the supply correspondence (defined for all  $p \in \mathbb{R}^N$ ).

If K is closed and convex and if S<sub>K</sub>(p̄) is nonempty and bounded, then there exists an open neighborhood P<sup>0</sup> of p̄ such that S<sub>K</sub> is nonempty-valued and upper semi-continuous on P<sup>0</sup>. (Proposition 3.18)

#### Proposition 9.6

Let  $K \subset \mathbb{R}^N$  be a nonempty closed convex set, and  $\pi_K : \mathbb{R}^N \to (-\infty, \infty]$  its support function, i.e.,  $\pi_K(p) = \sup_{x \in K} p \cdot x.$ Let  $\bar{p} \in \mathbb{R}^N$  be such that  $\pi_K(\bar{p}) < \infty$ . Then  $\pi_K$  is differentiable at  $\bar{p}$  if and only if there is a unique  $\bar{x} \in K$  such that  $\pi_K(\bar{p}) = \bar{p} \cdot \bar{x}.$ In this case,  $\nabla \pi_K(\bar{p}) = \bar{x}.$ 

### "If" part

- ▶ By the closedness and convexity of  $K \neq \emptyset$ , it follows from Proposition 3.18 that there exists an open neighborhood  $P^0$ of  $\bar{p}$  such that  $S_K$  is nonempty-valued and upper semi-continuous on  $P^0$ .
- ▶ The function  $f(x, p) = p \cdot x$  is differentiable in p, and  $\nabla_p f(x, p) = x$  is continuous in (x, p).
- With  $S_K(\bar{p}) = \{\bar{x}\}$ , the conclusion follows from Corollary 9.5.

## "Only if" part

• By the definition,  $S_K(p) \subset \partial \pi_K(p)$ .

Since  $\pi_K$  is convex, the differentiability of  $\pi_K$  at  $\bar{p}$  implies  $\partial \pi_K(\bar{p}) = \{\nabla \pi_K(\bar{p})\}.$ 

The nonemptiness of S<sub>K</sub>(p̄) follows from the differentiability of π<sub>K</sub> by an elementary argument under the closedness of K (see Oyama and Takenawa, Lemma A.5).

Hence,  $S_K(\bar{p})$  is a singleton.

▶ By the differentiability of  $\pi_K$ , we have  $\nabla \pi_K(\bar{p}) = \nabla_p (p \cdot x)|_{p=\bar{p}, x=\bar{x}} = \bar{x}$  for all  $\bar{x} \in S_K(\bar{p})$ . The convexity of K can be dropped if K is compact, in which case  $\operatorname{Co} K$  is closed.

Corollary 9.7 Let  $K \subset \mathbb{R}^N$  be a nonempty compact set. Then  $\pi_K$  is differentiable at  $\bar{p}$  if and only if there is a unique  $\bar{x} \in K$  such that  $\pi_K(\bar{p}) = \bar{p} \cdot \bar{x}$ . In this case,  $\nabla \pi_K(\bar{p}) = \bar{x}$ .

Show that 
$$S_{\operatorname{Co} K} = \operatorname{Co} S_K$$
.

- $\operatorname{Co} K$  is nonempty and closed if K is nonempty and compact.
- Therefore, it follows from Proposition 9.6 that

 $\begin{aligned} \pi_K &= \pi_{\operatorname{Co} K} \text{ is differentiable at } \bar{p} \\ \iff S_{\operatorname{Co} K}(\bar{p}) = \operatorname{Co} S_K(\bar{p}) \text{ is a singleton} \\ \iff S_K(\bar{p}) \text{ is a singleton}, \end{aligned}$ 

in which case  $S_K(\bar{p}) = \{\nabla \pi_K(\bar{p})\}.$ 

# Differentiability of the Indirect Utility Function

For  $p \in \mathbb{R}^N_{++}$  and  $w \in \mathbb{R}_{++}$ , consider the indirect utility function,  $v(p,w) = \sup\{u(x) \mid x \in B(p,w)\},$ 

and the Walrasian demand correspondence,

$$x(p,w) = \{ x \in \mathbb{R}^N_+ \mid x \in B(p,w), \ u(x) = v(p,w) \},\$$

where  $B(p, w) = \{x \in \mathbb{R}^N_+ \mid p \cdot x \le w\}.$ 

If u is continuous, then x is nonempty- and compact-valued and upper semi-continuous.

(Proposition 3.16)

#### Proposition 9.8

Assume that

- 1. u is locally insatiable and continuous,
- 2.  $x(\bar{p}, \bar{w}) = \{\bar{x}\}$ , and
- 3. for some j with  $\bar{x}_j > 0$  and for some neighborhoods  $X_j^0$  and  $X_{-j}^0$  of  $\bar{x}_j$  and  $\bar{x}_{-j}$  in  $\mathbb{R}_+$  and  $\mathbb{R}_+^{N-1}$ , respectively,  $\frac{\partial u}{\partial x_j}$  exists on  $X_j^0 \times X_{-j}^0$  and is continuous in x at  $\bar{x}$ . Then v is differentiable at  $(\bar{p}, \bar{w})$  with

$$\frac{\partial v}{\partial p_i}(\bar{p},\bar{w}) = -\frac{\frac{\partial u}{\partial x_j}(\bar{x})}{\bar{p}_j}\bar{x}_i, \quad \frac{\partial v}{\partial w}(\bar{p},\bar{w}) = \frac{\frac{\partial u}{\partial x_j}(\bar{x})}{\bar{p}_j}$$

for any j satisfying the condition in 3.

# Proof (1/3)

▶ By the local insatiability, the inequality constraint  $p \cdot x \leq w$  can be replaced by the equality constraint  $p \cdot x = w$ .

• Let 
$$x(\bar{p}, \bar{w}) = \{\bar{x}\}$$
, where  $\bar{p} \cdot \bar{x} = \bar{w}$ .

• Let 
$$j$$
,  $X_j^0$ , and  $X_{-j}^0$  be as in Assumption 3, where  
 $\bar{x}_j = \frac{1}{\bar{p}_j} \left( \bar{w} - \sum_{i \neq j} \bar{p}_i \bar{x}_i \right) \in X_j^0$ .

• Write 
$$x_{-j} = (x_1, ..., x_{j-1}, x_{j+1}, ..., x_N)$$
, and let

$$f(x_{-j}, p, w) = u\left(\frac{1}{p_j}\left(w - \sum_{i \neq j} p_i x_i\right), x_{-j}\right).$$

▶ As long as  $\frac{1}{p_j} \left( w - \sum_{i \neq j} p_i x_i \right) \in X_j^0$ , f is well defined and continuous, and  $\nabla_{(p,w)} f$  exists on a neighborhood of  $(\bar{x}_{-j}, \bar{p}, \bar{w})$  and is continuous in  $(x_{-j}, p, w)$  at  $(\bar{x}_{-j}, \bar{p}, \bar{w})$  by Assumption 3.

Proof (2/3)

▶ We claim that there exist open neighborhoods  $P^1$  and  $W^1$  of  $\bar{p}$  and  $\bar{w}$  and a compact neighborhood  $X^1_{-j} \subset \mathbb{R}^{N-1}_+$  of  $\bar{x}_{-j}$  such that

$$v(p,w) = \max_{x_{-j} \in X_{-j}^1} f(x_{-j}, p, w) \text{ for all } (p,w) \in P^1 \times W^1,$$

where

$$\arg\max_{x_{-j}\in X_{-j}} f(x_{-j}, \bar{p}, \bar{w}) = \{\bar{x}_{-j}\}.$$

▶ Then by Corollary 9.5, v is differentiable at  $(\bar{p}, \bar{w})$ , and

$$\begin{aligned} \frac{\partial v}{\partial p_i}(\bar{p},\bar{w}) &= \frac{\partial f}{\partial p_i}(\bar{x}_{-j},\bar{p},\bar{w}) = \frac{\partial u}{\partial x_j}(\bar{x})\frac{1}{p_j}(-\bar{x}_i),\\ \frac{\partial v}{\partial w}(\bar{p},\bar{w}) &= \frac{\partial f}{\partial w}(\bar{x}_{-j},\bar{p},\bar{w}) = \frac{\partial u}{\partial x_j}(\bar{x})\frac{1}{p_j}. \end{aligned}$$

# Proof (3/3)

•  $X_{-j}^1$ ,  $P^1$ , and  $W^1$  are constructed as follows: • Since  $\bar{x}_j = \frac{1}{\bar{p}_j} \left( \bar{w} - \sum_{i \neq j} \bar{p}_i \bar{x}_i \right) \in X_j^0$  and  $\frac{1}{p_j} \left( w - \sum_{i \neq j} p_i x_i \right)$  is continuous in  $(x_{-j}, p, w)$ , there exist open neighborhoods  $P^0$  and  $W^0$  of  $\bar{p}$  and  $\bar{w}$  and a compact neighborhood  $X_{-j}^1 \subset \mathbb{R}^{N-1}_+$  of  $\bar{x}_{-j}$  such that  $\frac{1}{p_j} \left( w - \sum_{i \neq j} p_i x_i \right) \in X_j^0$ for all  $(x_{-j}, p, w) \in X_{-j}^1 \times P^0 \times W^0$ .

Since x(p, w) is upper semi-continuous and  $x_{-j}(\bar{p}, \bar{w}) \subset X_{-j}^1$ , we can take open neighborhoods  $P^1 \subset P^0$  and  $W^1 \subset W^0$  of  $\bar{p}$  and  $\bar{w}$  such that  $x_{-j}(p, w) \subset X_{-j}^1$  for all  $(p, w) \in P^1 \times W^1$ .

# Differentiability of the Expenditure Function

For  $p \in \mathbb{R}^N_{++}$  and  $t \in [u(0), \bar{u})$ , where  $\bar{u} = \sup_{x \in \mathbb{R}^N_+} u(x)$  and we assume that  $u(0) < \bar{u}$ , consider the expenditure function,

$$e(p,t) = \inf\{p \cdot x \mid x \in V(t)\},\$$

and the Hicksian demand correspondence,

$$h(p,t) = \{ x \in \mathbb{R}^N_+ \mid x \in V(t), \ p \cdot x = e(p,t) \},\$$

where  $V(t) = \{x \in \mathbb{R}^N_+ \mid u(x) \ge t\}.$ 

- If u is upper semi-continuous, then h(p,t) is nonempty- and compact-valued and upper semi-continuous in p.
- If in addition, u is locally insatiable, then h(p,t) is upper semi-continuous in (p,t) and e(p,t) is continuous in (p,t).
   (Proposition 3.17)

## Proposition 9.9

#### Assume that

- $1. \ u$  is upper semi-continuous, and
- 2.  $h(\bar{p}, \bar{t}) = \{\bar{x}\}.$

Then e is differentiable in p at  $(\bar{p},\bar{t})$  with

$$\nabla_p e(\bar{p}, \bar{t}) = \bar{x}.$$

- By Proposition 3.17, the upper semi-continuity of u implies that h(p, t̄) is nonempty-valued and upper semi-continuous in p.
- The function  $f(x, p) = p \cdot x$  is differentiable in p, and  $\nabla_p f(x, p) = x$  is continuous in (x, p).

• With  $h(\bar{p}) = {\bar{x}}$ , the conclusion follows from Corollary 9.5.

#### Proposition 9.10

#### Assume that

1. u is locally insatiable and continuous,

2. 
$$h(\bar{p}, \bar{t}) = \{\bar{x}\}$$
, where  $\bar{t} > u(0)$ ,

3. for some 
$$j$$
 with  $\bar{x}_j > 0$  and for some neighborhoods  $X_j^0$  and  $X_{-j}^0$  of  $\bar{x}_j$  and  $\bar{x}_{-j}$  in  $\mathbb{R}_+$  and  $\mathbb{R}_+^{N-1}$ , respectively,  $\frac{\partial u}{\partial x_j}$  exists on  $X_j^0 \times X_{-j}^0$  and is continuous in  $x$  at  $\bar{x}$ , and

4.  $\frac{\partial u}{\partial x_j}(\bar{x}) \neq 0$  for some j satisfying the condition in 3. Then e is differentiable at  $(\bar{p}, \bar{t})$  with

$$\frac{\partial e}{\partial p_i}(\bar{p},\bar{t}) = \bar{x}_i, \quad \frac{\partial e}{\partial t}(\bar{p},\bar{t}) = \frac{\bar{p}_j}{\frac{\partial u}{\partial x_j}(\bar{x})},$$

for any j satisfying the condition in 3.

By the upper semi-continuity and local insatiability of u, e is continuous in (p, t).

▶ By the continuity of u, e(p,t) is a solution to the equation v(p, w) - t = 0 in w (which is unique by local insatiability), and x(p̄, w̄) = h(p̄, t̄) = {x̄}, where w̄ = e(p̄, t̄).
(See, e.g., Proposition 3.E.1 in MWG.)

Combined with Assumption 4, it follows from a version of the Implicit Function Theorem that the solution function e(p,t) to the equation v(p,w) - t = 0 in w is differentiable at  $(\bar{p},\bar{t})$  with

$$\begin{split} \frac{\partial e}{\partial p_i}(\bar{p},\bar{t}) &= -\frac{\frac{\partial v}{\partial p_i}(\bar{p},\bar{t})}{\frac{\partial v}{\partial w}(\bar{p},\bar{t})} = \bar{x}_i,\\ \frac{\partial e}{\partial t}(\bar{p},\bar{t}) &= -\frac{-1}{\frac{\partial v}{\partial w}(\bar{p},\bar{t})} = \frac{\bar{p}_j}{u_{x_j}(\bar{x})}, \end{split}$$

as claimed.

## Remark

• The continuity of  $\frac{\partial u}{\partial x_j}$  in x in Assumption 3 in Propositions 9.8 and 9.10 cannot be dropped.

See Oyama and Takenawa, Example 5.1.

**Concave Value Function** 

Let A be convex.

Proposition 9.11

Assume that

1. 
$$X^*(q) \neq \emptyset$$
 for all  $q \in A$ ,

2. for all  $x \in X$ ,  $f(x, \cdot)$  is differentiable, and

#### 3. v is concave.

Then v is differentiable at  $\bar{q}$  with

$$\frac{\partial v}{\partial q_s}(\bar{q}) = \frac{\partial f}{\partial q_s}(\bar{x}, \bar{q}), \qquad s = 1, \dots, S$$

for any  $\bar{x} \in X^*(\bar{q})$ .

## $\blacktriangleright$ If X is convex and f is concave in (x,q), then v is concave.