

Global Games

Daisuke Oyama

Topics in Economic Theory

October 4, 2024

Papers

- ▶ Carlsson, H. and E. van Damme (1993). “Global Games and Equilibrium Selection,” *Econometrica* 61, 989-1018.
- ▶ Frankel, D., S. Morris, and A. Pauzner (2003). “Equilibrium Selection in Global Games with Strategic Complementarities,” *Journal of Economic Theory* 108, 1-44.

Setting (FMP)

Global game $G(\kappa)$

- ▶ Players: $I = \{1, \dots, |I|\}$
- ▶ Actions of player i : $A_i = \{0, 1, \dots, n_i\}$
- ▶ State: $\theta \in \mathbb{R} \sim$ continuous density ϕ , connected support
- ▶ Payoffs of player i : $u_i(a, \theta)$
 - ▶ $\Delta u_i(a_i, a'_i, a_{-i}, \theta) = u_i(a_i, a_{-i}, \theta) - u_i(a'_i, a_{-i}, \theta)$
- ▶ Signal of player i : $x_i = \theta + \kappa \varepsilon_i$
 - ▶ $(\varepsilon_1, \dots, \varepsilon_{|I|}) \sim$ continuous joint density f , support contained in $[-\frac{1}{2}, \frac{1}{2}]^I$
 - ▶ Independent of θ

Assumptions

1. Strategic complementarities:

For all $i \in I$,

if $a_i \geq a'_i$ and $a_{-i} \geq a'_{-i}$, then

$\Delta u_i(a_i, a'_i, a_{-i}, \theta) \geq \Delta u_i(a_i, a'_i, a'_{-i}, \theta)$ for all θ .

2. Dominance regions:

There exist $\underline{\theta}$ and $\bar{\theta}$ such that for all $i \in I$,

- ▶ if $\theta \leq \underline{\theta}$, then $\Delta u_i(0, a_i, a_{-i}, \theta) > 0$ for all $a_i \neq 0$ and all a_{-i} ;
and
- ▶ if $\theta \geq \bar{\theta}$, then $\Delta u_i(n_i, a_i, a_{-i}, \theta) > 0$ for all $a_i \neq n_i$ and all a_{-i} .

3. Strict state monotonicity:

There exists $K_0 > 0$ such that for all $i \in I$ and all a_{-i} ,
if $a_i \geq a'_i$ and $\theta \geq \theta'$, then

$$\Delta u_i(a_i, a'_i, a_{-i}, \theta) - \Delta u_i(a_i, a'_i, a_{-i}, \theta') \geq K_0(a_i - a'_i)(\theta - \theta').$$

4. Payoff continuity:

For all $i \in I$ and all a , $u_i(a, \theta)$ is continuous in θ .

Two Players, Two Actions (Carlsson and van Damme)

► $I = \{1, 2\}$, $A_1 = A_2 = \{0, 1\}$

► Payoffs:

	0	1
0	0	0
1	$-p_i(\theta)$	$1 - p_i(\theta)$

► $p_i(\theta)$: continuous, strictly decreasing

► $p_i(\theta) > 1$ if $\theta \leq \underline{\theta}$ ($\Rightarrow$ action 0 is dominant)

$p_i(\theta) < 0$ if $\theta \geq \bar{\theta}$ ($\Rightarrow$ action 1 is dominant)

► For θ such that $0 < p_i(\theta) < 1$, $i = 1, 2$,
(0, 0) and (1, 1) are strict Nash equilibria.

► Risk-dominance in asymmetric 2×2 coordination games:

► $(1, 1)$ risk-dominant at θ

$$\iff p_1(\theta)p_2(\theta) < (1 - p_1(\theta))(1 - p_2(\theta))$$

$$\iff p_1(\theta) + p_2(\theta) < 1$$

► $(0, 0)$ risk-dominant at θ

$$\iff p_1(\theta)p_2(\theta) > (1 - p_1(\theta))(1 - p_2(\theta))$$

$$\iff p_1(\theta) + p_2(\theta) > 1$$

► Let θ^* be the unique θ such that

$$p_1(\theta) + p_2(\theta) = 1$$

► $(1, 1)$ risk-dominant at θ iff $\theta > \theta^*$

► $(0, 0)$ risk-dominant at θ iff $\theta < \theta^*$

Simplifying Assumptions

- ▶ Uniform prior:

ϕ uniform on some $[a, b]$ (sufficiently large)

- ▶ Private values:

Payoffs $u_i(a, x_i)$, depending on signal x_i (rather than θ)

Equilibrium Selection

Theorem 1 (Two-player, two-action case)

In the limit as $\kappa \rightarrow 0$, an essentially unique strategy profile survives iterative dominance; and it plays the risk-dominant equilibrium.

Posterior Beliefs

- ▶ f^κ : joint density of $(\kappa\varepsilon_1, \kappa\varepsilon)$

$$(f^\kappa(z_1, z_2) = \frac{1}{\kappa^2} f(\frac{z_1}{\kappa}, \frac{z_2}{\kappa}))$$

- ▶ Conditional density (for x_1, x_2 away from the boundary):

$$\begin{aligned} f_1^\kappa(x_2|x_1) &= \frac{\int f^\kappa(x_1 - \theta, x_2 - \theta)\phi(\theta)d\theta}{\iint f^\kappa(x_1 - \theta, x_2 - \theta)dx_2\phi(\theta)d\theta} \\ &= \frac{\int f^\kappa(x_1 - \theta, x_2 - \theta)d\theta}{\iint f^\kappa(x_1 - \theta, x_2 - \theta)dx_2d\theta} \\ &= \int f^\kappa(x_1 - \theta, x_2 - \theta)d\theta \\ f_2^\kappa(x_1|x_2) &= \cdots = \int f^\kappa(x_1 - \theta, x_2 - \theta)d\theta \end{aligned}$$

- Density of $\kappa\varepsilon_1 - \kappa\varepsilon_2$:

$$\psi^\kappa(y) = \int f^\kappa(z + y, z) dz$$

- Thus,

$$\begin{aligned} f_1^\kappa(x_2|x_1) &= f_2^\kappa(x_1|x_2) = \int f^\kappa(x_1 - \theta, x_2 - \theta) d\theta \\ &= \int f^\kappa(z + x_1 - x_2, z) dz \\ &= \psi^\kappa(x_1 - x_2) \end{aligned}$$

► Therefore,

$$\begin{aligned}P(x_2 \geq \xi_2 | x_1 = \xi_1) &= \int_{x_2 \geq \xi_2} \psi^\kappa(\xi_1 - x_2) dx_2 \\&= \int_{x_1 \leq \xi_1} \psi^\kappa(x_1 - \xi_2) dx_1 \\&= 1 - P(x_1 \geq \xi_1 | x_2 = \xi_2)\end{aligned}$$

or

$$P(x_2 \geq \xi_2 | x_1 = \xi_1) + P(x_1 \geq \xi_1 | x_2 = \xi_2) = 1 \quad (*)$$

Iterative Dominance

- ▶ By Dominance regions, player i observing a signal above some threshold $\bar{\xi}_i^1$ play 1.
- ▶ Assuming that player j with signals above $\bar{\xi}_j^1$ play 1,
by Action monotonicity and State monotonicity, player i observing a signal above some threshold $\bar{\xi}_i^2$ play 1, where $\bar{\xi}_i^2 \leq \bar{\xi}_i^1$.
- ▶ ...
- ▶ We have $\bar{\xi}_i^1 \geq \bar{\xi}_i^2 \geq \dots \searrow \bar{\xi}_i$.
- ▶ Similarly, from below we have $\underline{\xi}_i^1 \leq \underline{\xi}_i^2 \leq \dots \nearrow \underline{\xi}_i$.
- ▶ All these depend on κ ;
write the limits as $\bar{\xi}_i(\kappa)$ and $\underline{\xi}_i(\kappa)$.

- ▶ By continuity, player 1 with signal $\bar{\xi}_1(\kappa)$ when opponents play 1 above $\bar{\xi}_2(\kappa)$ and 0 below $\bar{\xi}_2(\kappa)$ must be indifferent between playing 1 and 0:

$$P(x_2 \geq \bar{\xi}_2(\kappa) | x_1 = \bar{\xi}_1(\kappa)) = p_1(\bar{\xi}_1(\kappa))$$

- ▶ Similarly,

$$P(x_1 \geq \bar{\xi}_1(\kappa) | x_2 = \bar{\xi}_2(\kappa)) = p_2(\bar{\xi}_2(\kappa))$$

- ▶ In particular, it must be that $|\bar{\xi}_1(\kappa) - \bar{\xi}_2(\kappa)| < \kappa$.
- ▶ By (*), we have

$$p_1(\bar{\xi}_1(\kappa)) + p_2(\bar{\xi}_2(\kappa)) = 1.$$

- ▶ Let $(\bar{\xi}^*, \bar{\xi}^*)$ be any limit point of $(\bar{\xi}_1(\kappa), \bar{\xi}_2(\kappa))$ as $\kappa \rightarrow 0$.
- ▶ By continuity, we have

$$p_1(\bar{\xi}^*) + p_2(\bar{\xi}^*) = 1.$$

- ▶ Therefore, we must have $\bar{\xi}^* = \theta^*$.
- ▶ It follows that $\bar{\xi}_1(\kappa)$ and $\bar{\xi}_2(\kappa)$ both converge to θ^* as $\kappa \rightarrow 0$.
- ▶ Symmetrically, $\underline{\xi}_1(\kappa)$ and $\underline{\xi}_2(\kappa)$ both converge to θ^* as $\kappa \rightarrow 0$.
- ▶ Hence, in the limit as $\kappa \rightarrow 0$, the game is dominance solvable, and the surviving strategy profile plays $(1, 1)$ if $\theta > \theta^*$ and $(0, 0)$ if $\theta < \theta^*$.

Many Players, Many Actions (FMP)

- ▶ Limit Uniqueness
- ▶ Noise dependence of the surviving strategy profile
- ▶ Sufficient conditions for noise independence
 - ▶ Two-player two-action case
 - ▶ ...

Limit Uniqueness

Theorem 2

$G(\kappa)$ has an essentially unique strategy profile surviving iterative dominance in the limit as $\kappa \rightarrow 0$.

More precisely, there exists an increasing pure strategy profile s^ such that if for each $\kappa > 0$, s^κ is a pure strategy profile surviving iterative dominance in $G(\kappa)$, then $\lim_{\kappa} s^\kappa(x) = s^*(x)$ for all x but except possibly for finitely many discontinuous points of s^* .*

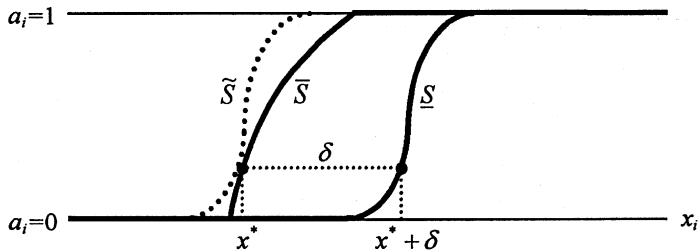


Fig. 4.

(From FMP 2003, p.8)

Global Game Selections

- ▶ Let θ^* be a point at which s^* is continuous.
- ▶ $s^*(\theta^*)$ is a Nash equilibrium of the complete information game $(u_i(\cdot, \theta^*))_{i \in I}$.
- ▶ Say that $s^*(\theta^*)$ is a *global game selection* in $(u_i(\cdot, \theta^*))_{i \in I}$.

Noise Dependence

- ▶ In general, global game selection is noise dependent.
There are games in which different equilibria are selected under different noise distributions f_i .
- ▶ On the other hand, global game selection does not depend on the prior distribution ϕ , and how $(u_i(\cdot, \theta))_{i \in I}$ behaves for $\theta \neq \theta^*$ (as long as the assumptions are satisfied).

Noise Independence

- ▶ In certain games, global game selection is independent of the noise distribution.
- ▶ Carlsson and van Damme (1993) showed that in 2×2 coordination games, a risk-dominant equilibrium is a noise-independent global game selection.
- ▶ FMP show:
if the game has a “local potential” (LP) function and satisfies own-action [concavity](#), then the LP-maximizer is a noise-independent global game selection.
- ▶ More generally,
if the game has a “monotone potential” (MP) function, then the MP-maximizer is a noise-independent global game selection.

Table 1
Noise (in)dependence in supermodular games.

Symmetric games				Asymmetric games			
actions:	2 each	3 each	4 each	actions:	2 each	2 by n	3 each
2 players	✓ ^a	✓ ^c	✗ ^b	2 players	✓ ^a	✓ ^g	✗ ^c
3 players	✓ ^b	✗ ^d		3 players	✗ ^e	n/a	
n players	✓ ^b			n players	✗ ^f	n/a	

✓ Always noise independent. ✗ Counterexample to noise independence exists. For empty cells noise dependence follows from an example in smaller games.

^a Carlsson and Van Damme [6].

^b Frankel, Morris and Pauzner [10].

^c Basteck and Daniëls [1].

^d Basteck et al. [2].

^e Carlsson [4].

^f Corsetti et al. [7].

^g This paper, see Section 5: Two-player games with 2 by n actions.

(From Basteck, Daniels, and Heinemann 2013, p.2629)